

ELROB 2018

24 - 28 September 2018
Mons, Belgium

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REAL TASKS, IN A REAL WORLD SCENARIO

Transport – Convoying

Military transport tasks can be roughly divided into two broad areas, those for dismounted soldiers and those for vehicles, e.g. trucks as a part of convoys.

Movements of personnel, material, humanitarian aid etc. are routine tasks on missions. In hostile environment these movements are dangerous, because convoys always attract attacks like roadside IEDs etc.

Environment:

Semi-urban terrain with roads ranging from streets (covered, e.g., with asphalt, loose chippings or concrete) to simple dirt paths; grass, sand, water, stones; ditches and trenches or any kind of other obstacles.

Situation:

There is a delivery for a camp within approx. 2.5 km. A group of at least two vehicles has to be moved to this camp.

There will be dynamic objects and static obstacles in the area. Dead ends, sharp turns, road blockings and narrow passages might occur. Barricades, barriers or any kind of blockades can be expected. Beware of negative obstacles.

Objective:

Move at least two vehicles of min. 50kg each to the target location as fast as possible and with highest autonomy possible. Only one operator is allowed to control the vehicles. There is only one control station allowed, either vehicle-mounted or stationary outside the vehicles.

The team will receive a section of a digital map with UTM co-ordinates that specify the waypoints which have to be traversed in the given order; see example in the rules. The vehicles cannot just drive straight lines between the waypoints but have to identify and navigate along roads and paths.

Actually, the route to the target location is a round course which leads back to the starting point. At least two such laps of 2.5 km each have to be driven; further laps are possible and desirable.

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Deliver the driven path as UTM coordinate list and plot it into the digital map (see rules for format description). If possible, transmit live position and video imagery to the control station.

Additionally, search for Objects of Potential Interest (OPI), i.e. particular markers with special characteristics as defined in the rules. Whenever an OPI is found, acquire imagery and mark its position inside the digital map.

Report all gathered data to the control station, online or offline after having returned to the starting point.

Remarks:

- Be prepared to deliver additional data in ROS bag format; exact specification and data types will follow.

Timing:

Duration approx. 40 min. The scenario can be finished whenever the vehicles arrive at the target location (i.e. return to the starting point) or ends with reaching the time limit. In either case, the transmission of the acquired data must take place within the time limit.

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